Daniel J. Rivera

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Education

<u>Education</u>	
Northern Arizona University	
- BSE Mechanical Engineering (4.0 GPA)	Class of 2020
- Minor in Mathematics (4.0 GPA)	2019
- Minor in Biology (4.0 GPA)	2018
Coconino Community College:	
- Associates in Applied Science (4.0 GPA)	2016
- Emergency Medical Technician (9 credit certification, 4.0 GPA)	2013
- Firefighter 1&2 (9 credit certification, 4.0 GPA)	2013
<u>Awards</u>	
Goldwater Scholarship	2018
- The most prestigious undergraduate STEM scholarship in America	
- Awarded for research in muscle modeling, GPA, and intent to pursue	
research career in wearable robotics and bio-inspired control	
 Northern Arizona University: Hooper Undergraduate Research Grant 	2017
Awarded \$3,400 in funding for muscle modeling research	2017
- CCC2NAU Raymond Scholarship	2016-2017
 Awarded \$4,000 for GPA accomplishments 	
- GEMS Scholarship	2016-2018
 Awarded ~\$6,600 per year for 2 years for GPA accomplishments 	
• Coconino Community College:	
- Student of the Year for academic excellence in Applied Mathematics	2016
 Awarded for GPA, community building, and tutoring, 	
And career aspirations.	
- NREMT/FF1&2 Certification	2014
• Other:	
- Black Belt (Hapkido, Jujutsu CQDT cert.)	2006
Publications	
"Case Study: A Bio-inspired Control Algorithm for a Robotic	2017
Foot-Ankle Prosthesis Provides Robust Control of Level Walking	
and Stair Ascent."	
- Coauthor. Frontiers: https://doi.org/10.3389/frobt.2018.00036	
• "Verification of a Winding Filament Muscle Model"	2020
- First Author, to be submitted spring 2020	
<u>Presentations</u>	
• Dynamic Walking (IHMC Robotics, Pensacola FL)	2018
- Only undergraduate speaker	

Presented sum of research from 2016-2018

Link: https://youtu.be/3F9x2IuS-ig

Biomedical Engineering Society (Phoenix, AZ) 2017 Poster presentation of OpenSim muscle modelling research Society for Integrative and Comparative Biology (New Orleans, LA) 2016 Poster presentation of mouse soleus muscle modelling research **Recently Funded Projects:** Biomechatronics Lab (\$6,000 via NSF grant), NAU

2018-2019

- Developed controller for motorized lower limb prosthesis
- Device is for patients with stroke induced weakness/lower leg
- Controller is based off of previous and current modelling research

Biomechatronics Lab (\$3,400 via HURA grant), NAU

2017-2018

- Test whether implementing muscle model developed through previous research can improve whole-body simulations in OpenSim
- Implemented muscle model in OpenSim through MATLAB interface
- Compared muscle model predictions in lower body, 54 muscle, 23 degree of freedom simulations.

Center for Bioengineering Innovation (\$10,000 via CBI), NAU

2016-Ongoing

- Test whether including role for protein titin in muscle models can simulate length dependent changes in muscle forces
- Comparisons made against ex-vivo mouse soleus experiments performed at NAU
- Developed model of muscle activation to allow simulation of ex-vivo experiments
- Helped conduct in person trials that show benefit of model for prosthesis applications

Unfunded Projects:

"Air-Vest" Head Protection System, NAU

2018

- Light-weight wearable airbag vest for trail runners and cyclists
- ANSYS simulations found design lowers head accelerations 30% compared to traditional helmets
- Comparable cost and function with existing smart helmets
- Increased wearer safety and comfort

"The 33 Special" Drone, NAU

2017

- 3D printed competition drone designed for mid-air impact
- Won best design in class
- Won most creative design in student cohort

Research Interests

- Mathematical descriptions of biological systems and their use as control algorithms
- Biomimetics, bio-inspired design of assistive/rehabilitative wearable devices

Recent Work Experience

• Ottobock, Cambridge MA

Sum '19

- Implemented muscle-based control algorithm in wearable robotic ankle
- Self-taught embedded systems approach to robotic control
- Updated s-wifi protocol and hardware
- Assisted with development of new wearable devices

• Center for Bioengineering Innovation, NAU

2016-20

- Developed new muscle model based on winding filament hypothesis
- Assisted with testing of motorized ankle prosthesis
- Hands-on work with patients with trans-tibial amputations

• Science Lab, CCC

2015

- Prepared equipment, chemicals, organisms, and experiments for classroom use
- Maintained communication with instructors to adapt lab schedule
- Worked independently with hazardous materials and infectious organisms
- Maintained lab safety and cleanliness to state and county standards

• Guardian Medical Transport

2013-14

- Responded to 911 emergencies by ambulance
- Integrated with variable agencies at emergency scenes
- Effectively communicate with patients, their families, and hospital staff
- Documented patient contact above standards set by Guardian Medical Transport

• "Pizza Guy" Pizza Delivery

2012-2013

- Manager, cook, and driver
- Accounting duties, supply order
- Comedic relief

Volunteer Experience

- Flagstaff Care and Share Food Bank
- Flagstaff Soup Kitchen
- Northern Arizona Humane Society

<u>Associations\Fraternities\Clubs</u>

- Tau Beta Pi Engineering Honor Society (Northern Arizona University)
 - Active Member
- Center for Bioengineering Innovation (Northern Arizona University)
 - Undergraduate researcher
- Biomechatronics Laboratory (Northern Arizona University)
 - Undergraduate researcher

References

- Rick Casler
 Former VP of R&D, BionX
 408-921-0293
- Kiisa C. Nishikawa, Ph.D.
 Director, NAU Center for Bioengineering Innovation
 Regents Professor
 kiisa.nishikawa@nau.edu
- Zachary Lerner, Ph.D
 Director, NAU Biomechatronics Lab
 Assistant Professor
 zachary.lerner@nau.edu
- Shawn Nittman
 Biology Instructor, CCC
 Wildland Search & Rescue
 shawn.nittman@coconino.edu